## Martin Bies

Homework 5 – Coding

Due: Thursday, February 24 – 10:00 am EST

## Problem 1C: Transformation matrix [20 Points]

- 1. Write a Python function: Input: Two basis  $\mathcal{B}_1$ ,  $\mathcal{B}_2$  of  $\mathbb{R}^n$ . Output:  $T_{\mathcal{B}_2\mathcal{B}_1}$ .
- 2. Write a Python function: Input: Two basis  $\mathcal{B}_1$ ,  $\mathcal{B}_2$  of  $\mathbb{R}^n$  and  $A_{\mathcal{B}_1 \mathcal{B}_1}$  Output:  $A_{\mathcal{B}_2 \mathcal{B}_2}$ .
- 3. We will now identify a basis  $\mathcal{B}'$  such that  $\varphi \colon \mathbb{R}^3 \to \mathbb{R}^3$  is easy:

$$A_{\mathcal{B}\mathcal{B}} = \begin{bmatrix} 3/2 & 1/2 & 0\\ 1/2 & 3/2 & 0\\ 0 & 0 & 3 \end{bmatrix}, \qquad \mathcal{B} = \left\{ \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1 \end{bmatrix} \right\}$$
(1)

• Rotate the standard basis  $\mathcal{B}$  by  $\alpha \in I = \{0^\circ, 1^\circ, \dots, 720^\circ\}$  about the z-axis:

$$\mathcal{B}' = \{ R_z \vec{e_1}, R_z \vec{e_2}, R_z \vec{e_3} \} , \quad R_z = \begin{bmatrix} \cos(\alpha) & \sin(\alpha) & 0 \\ -\sin(\alpha) & \cos(\alpha) & 0 \\ 0 & 0 & 1 \end{bmatrix} .$$
(2)

For all  $\alpha \in I$ , verify that  $\mathcal{B}'$  is a basis.

Hint: Use your function from homework 4.

- Compute  $A_{\mathcal{B}'\mathcal{B}'}$  with 5 digit precision for all angles  $\alpha \in I$ .
- For which  $\alpha \in I$  is  $A_{\mathcal{B}'\mathcal{B}'}$ , as computed by Python, approximately diagonal?